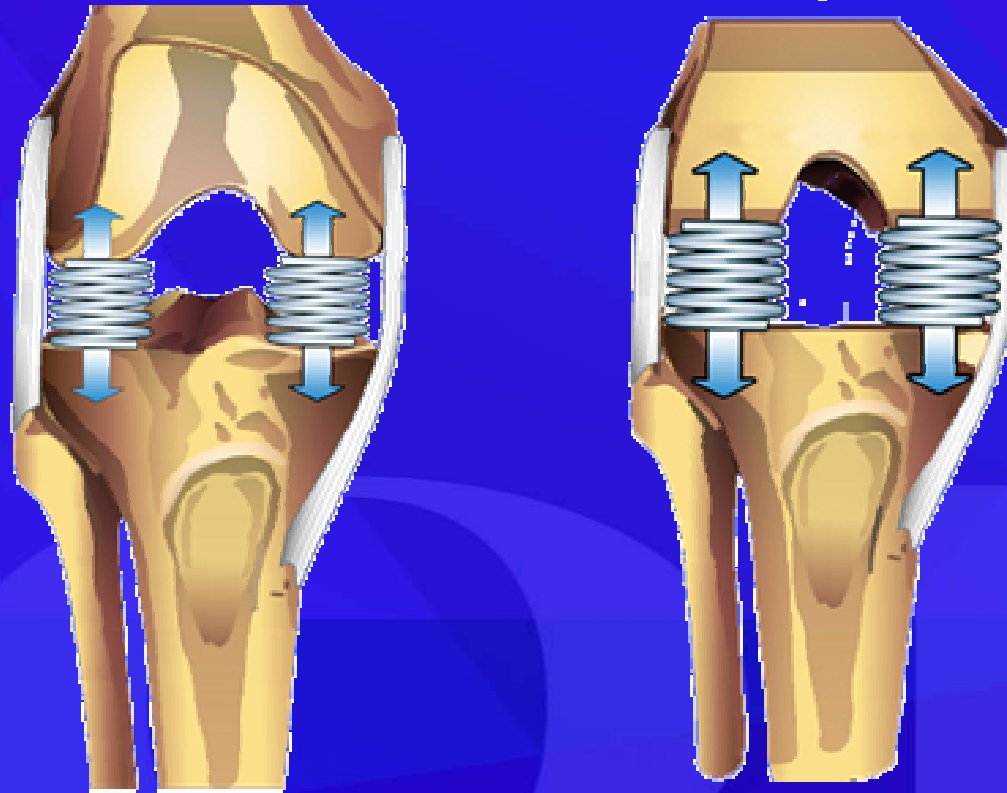


# SENSOR TENSOR

# SENSOR TENSOR

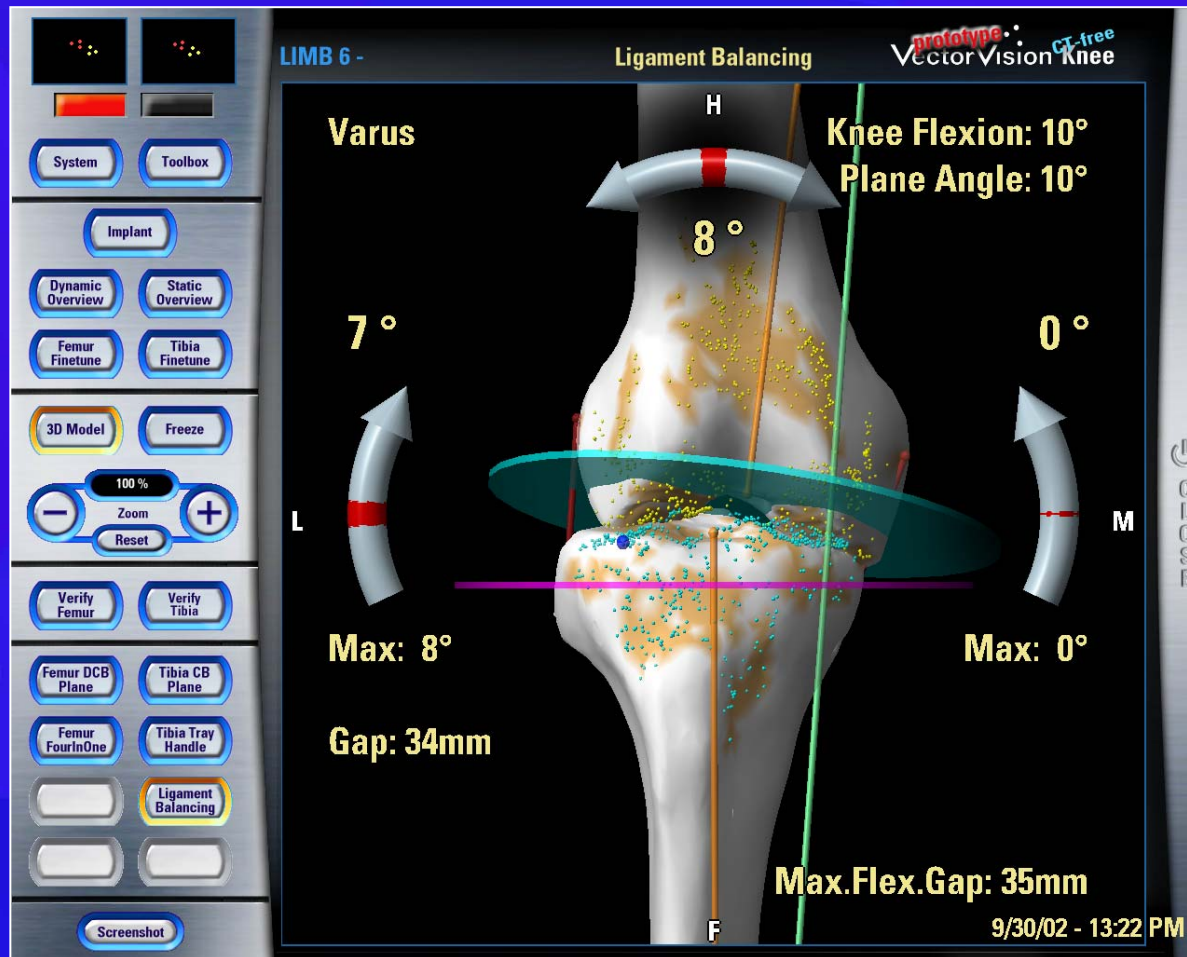
## TENSOR GOAL

- ✓ **APPLY CONSTANT FORCES IN BOTH COMPARTMENTS**



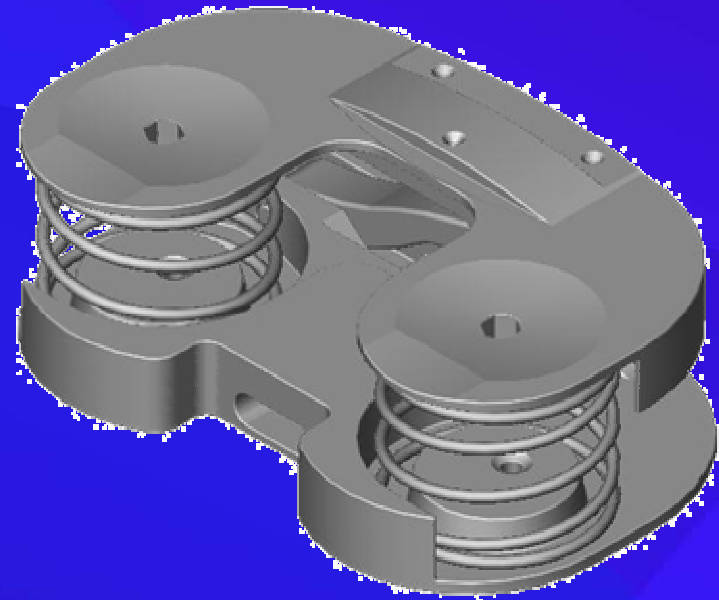
# SENSOR TENSOR

## MONITOR BALANCE DURING ROM

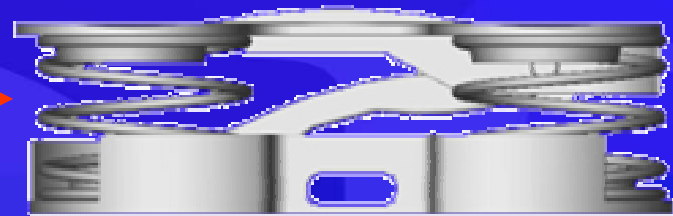


# SENSOR TENSOR

**2 PADS**

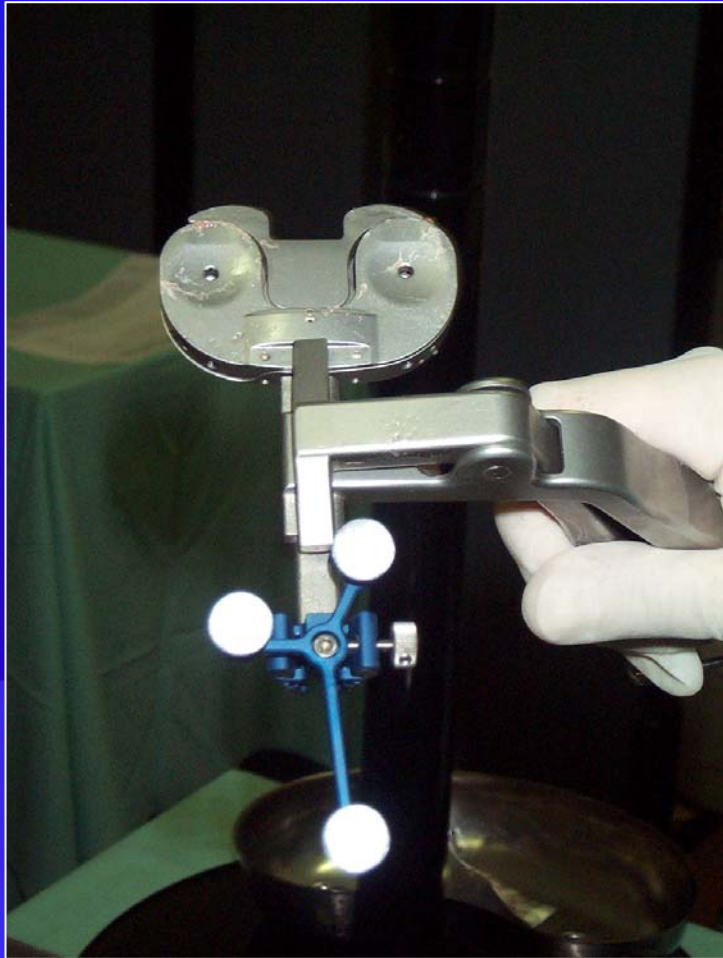


**SEPARATED  
BY 2 SPRINGS**



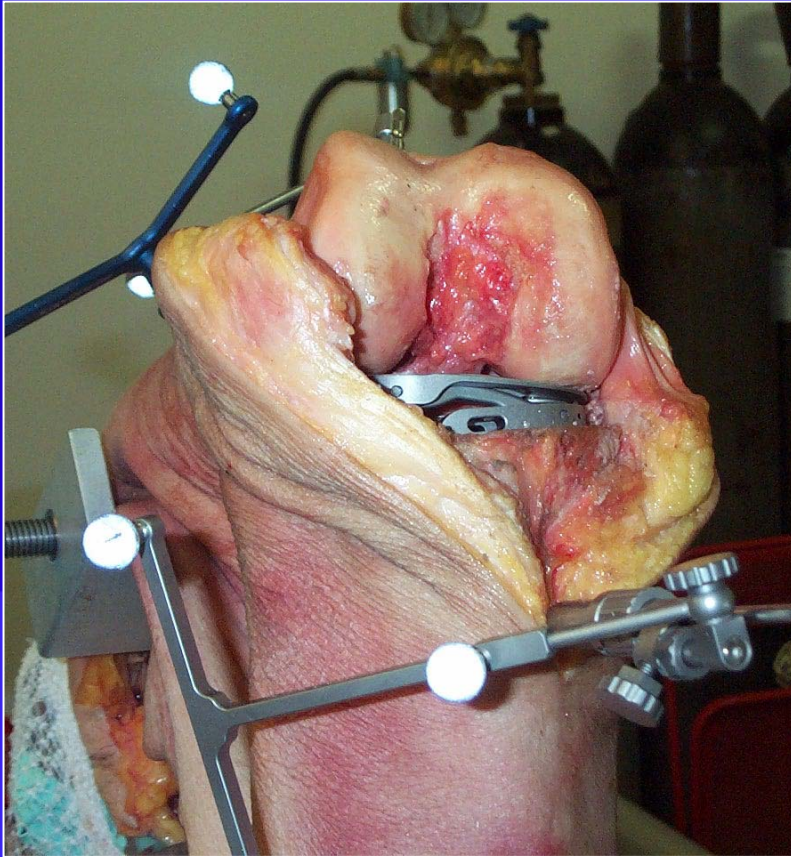
# SENSOR TENSOR

## POSSIBILITY OF REGISTRATION

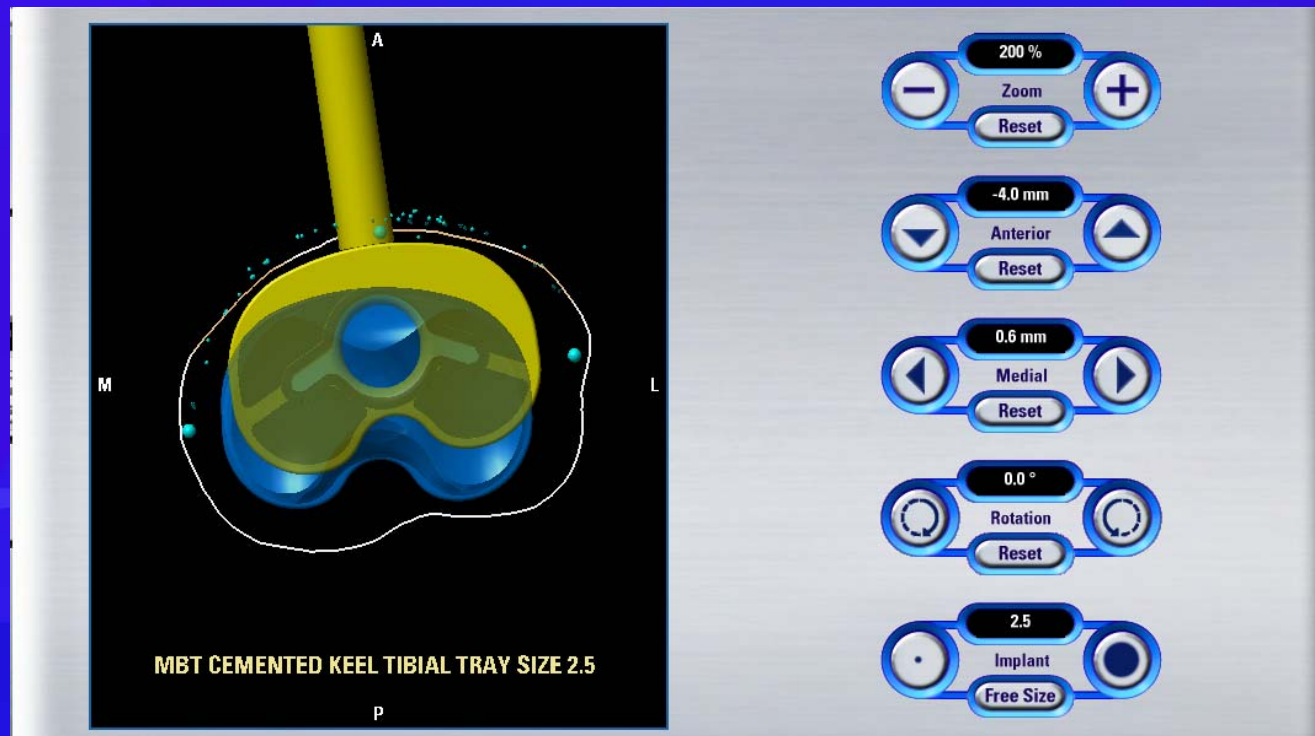




## POSSIBILITY OF NAVIGATION



## ENSURING HIGH REPEATABILITY AND POSITIONING CONTROL



# SENSOR TENSOR

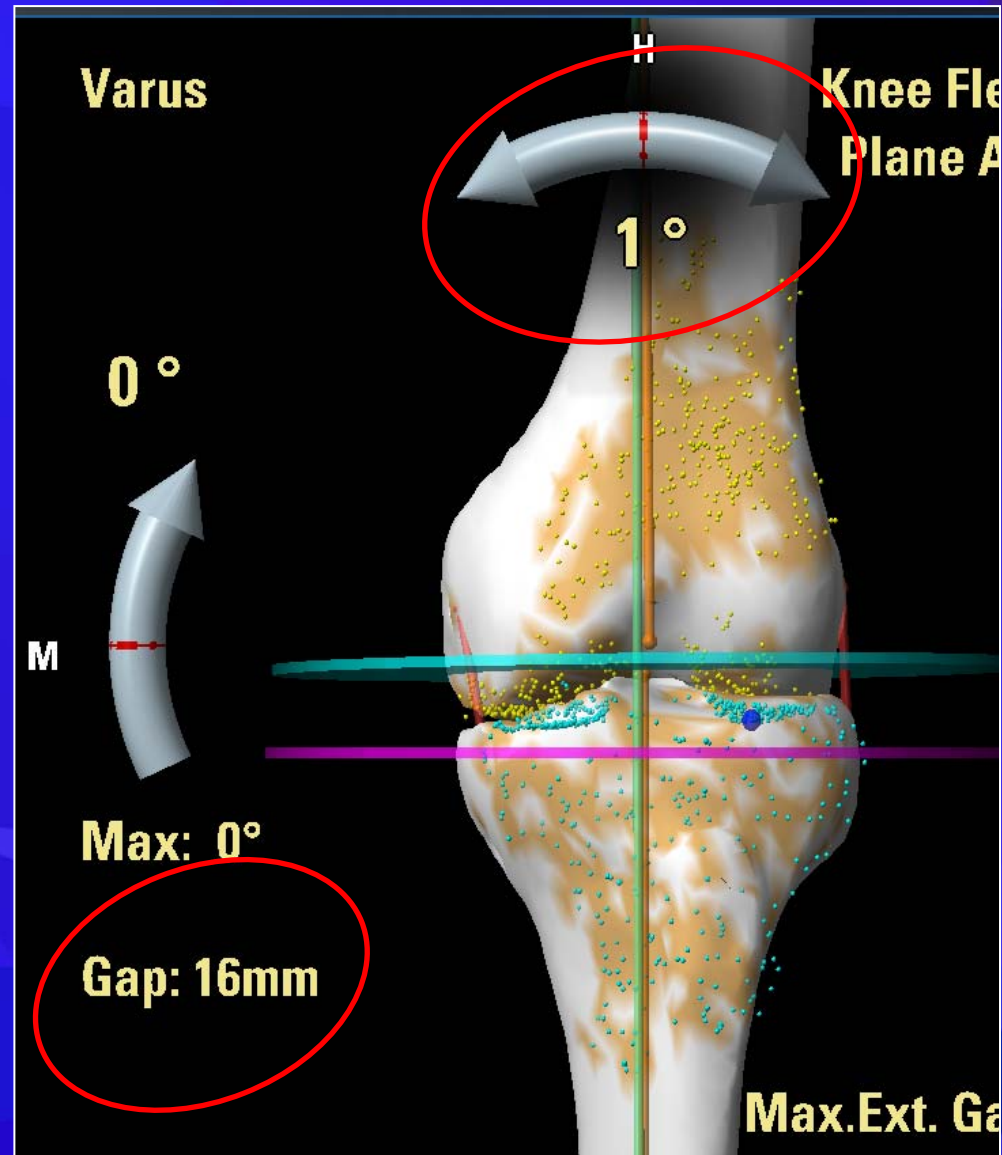
**TIBIAL CUT  
EXECUTION**



**TEST TO CONTROL**



**SPACE AND  
BALANCE AT THE  
SAME TIME**

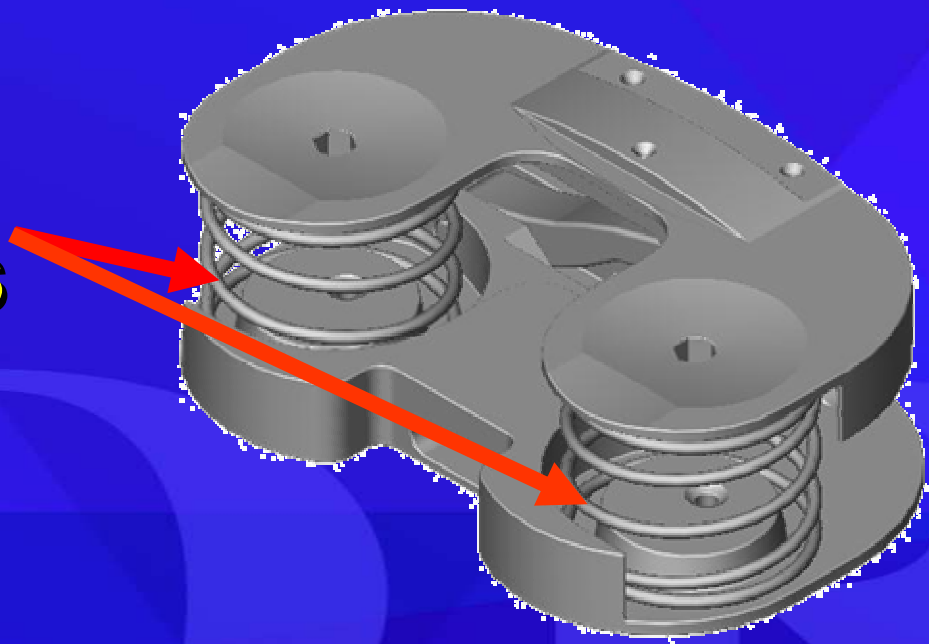




## TENSOR VALIDATION

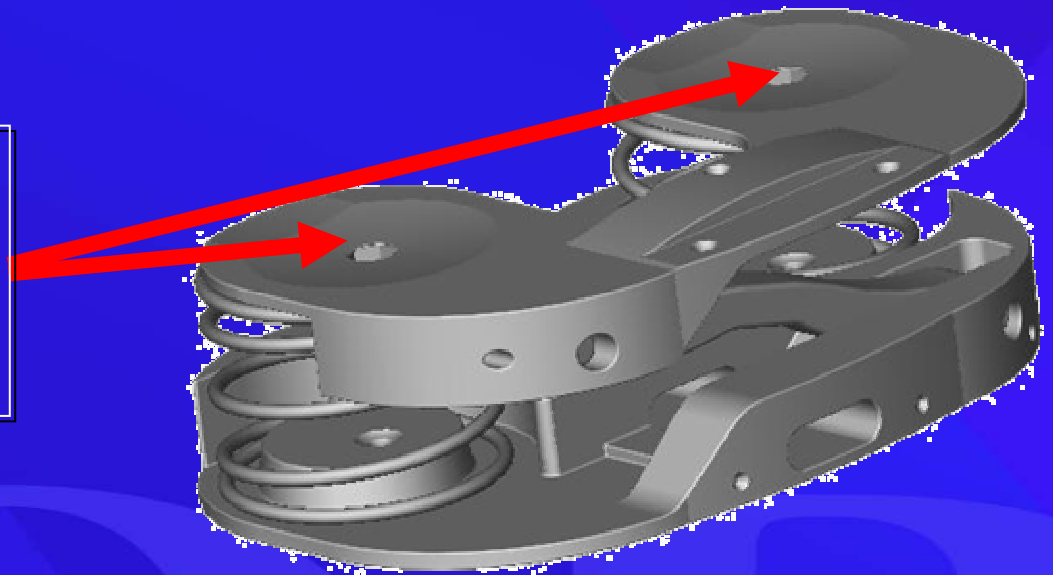
✓ **FEW DATA ABOUT FORCES IN LITERATURE**

✓ **VALIDATION OF  
3, 6, 9KG SPRINGS**



## TENSOR VALIDATION

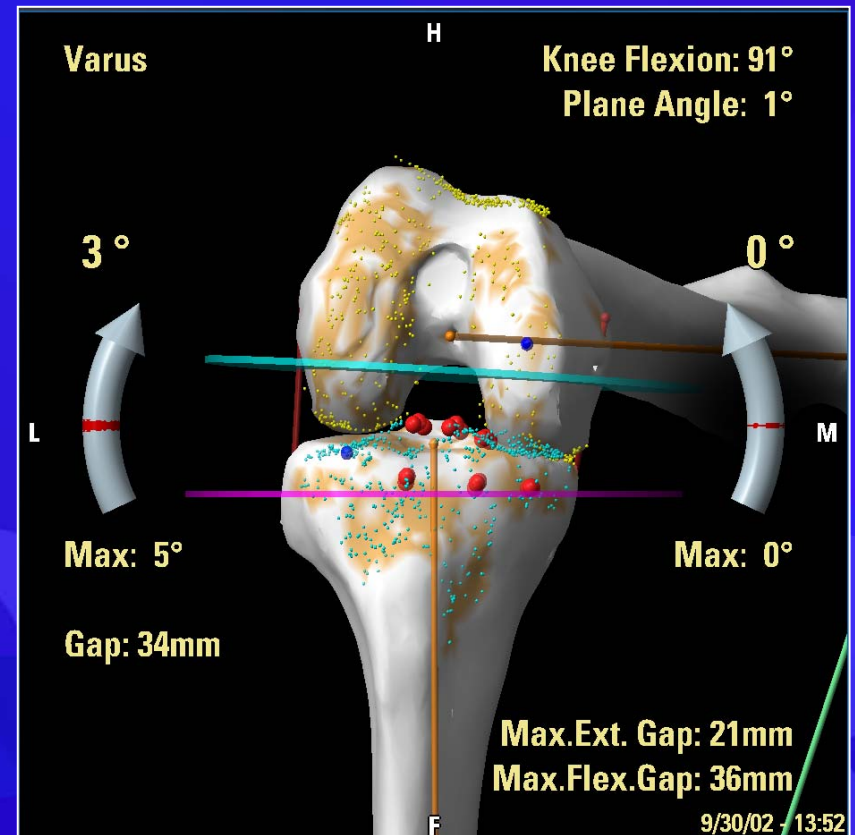
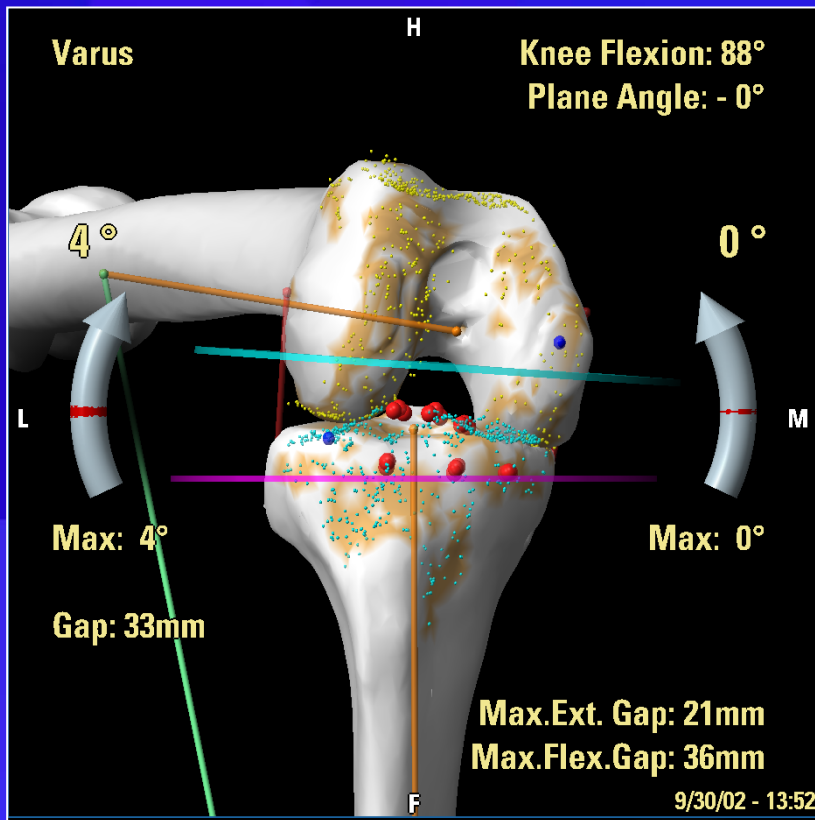
**FLAT ROUNDED  
FEMORAL  
SURFACES**



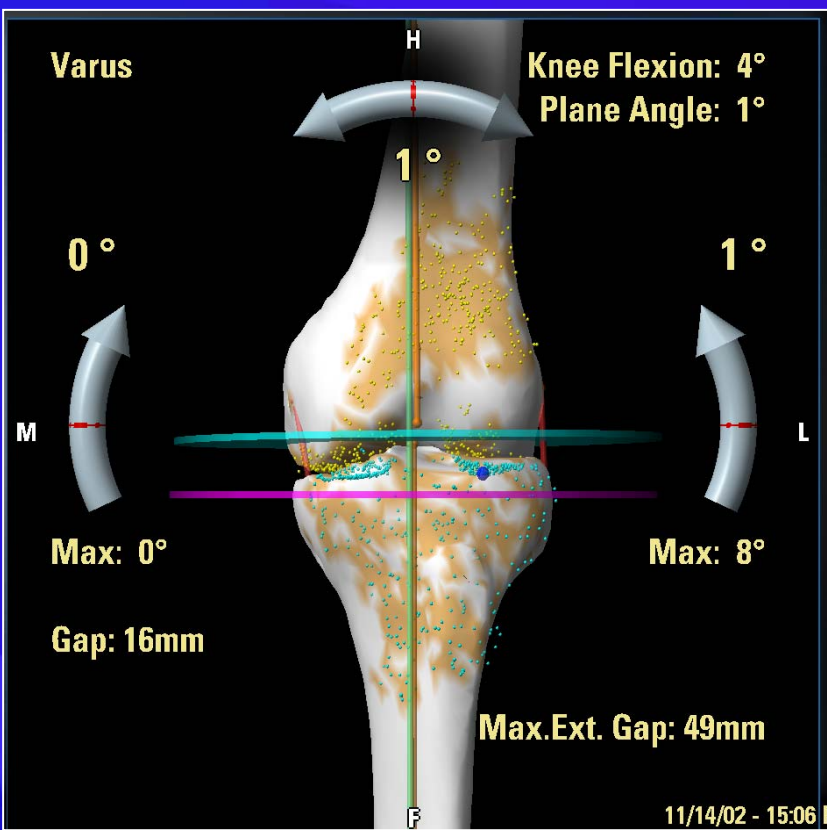
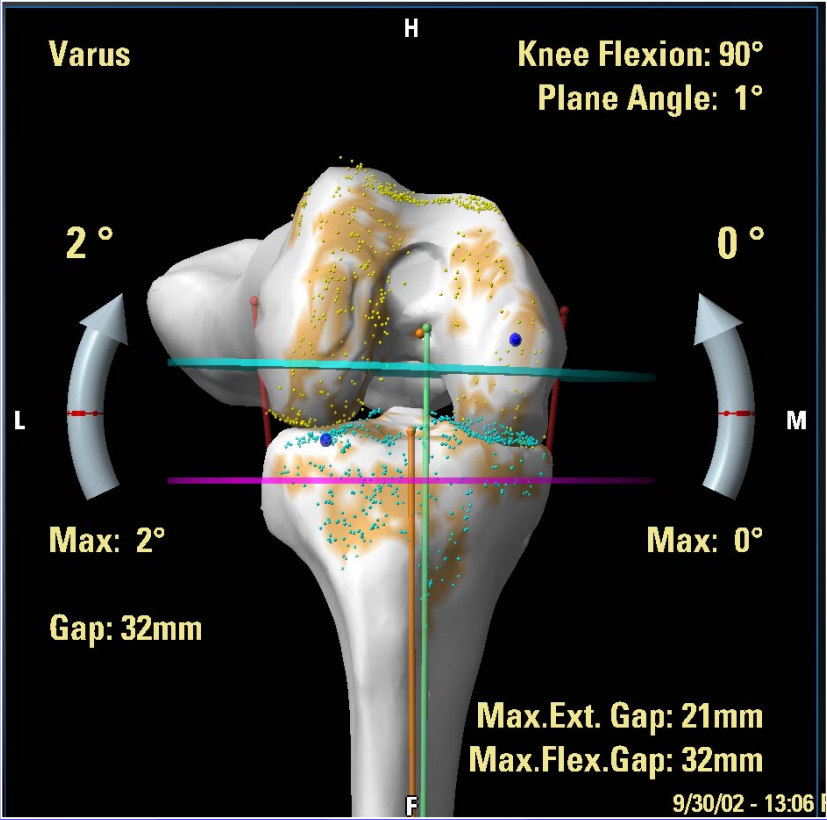
# SENSOR TENSOR

## TENSOR VALIDATION

### REPEATABILITY OF MEASUREMENTS



## TENSOR VALIDATION

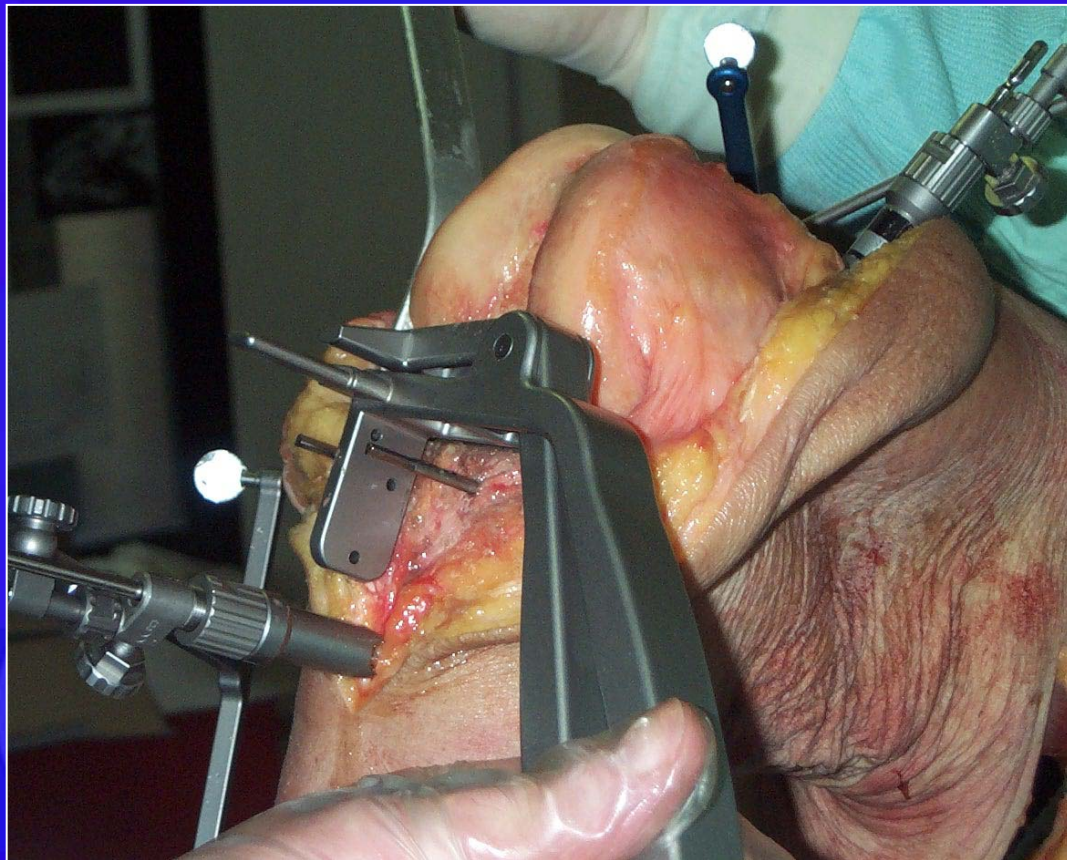




# SENSOR TENSOR

## TENSOR VALIDATION

### USABILITY OF TOOL



# RESULTS



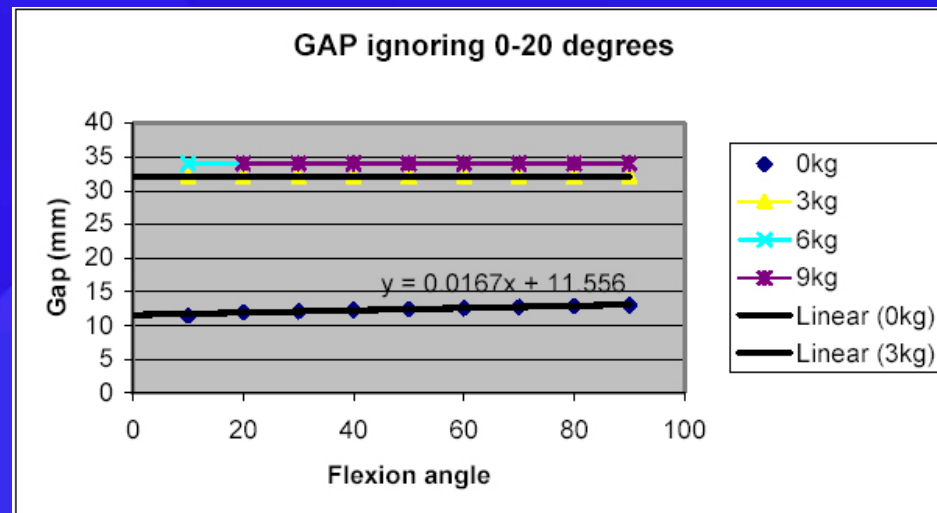
**INCREASED QUALITATIVE AND  
QUANTITATIVE  
INFORMATION RESPECT TO  
NORMAL SPACERS**

# RESULTS

## INCREASED SPRING FORCE



## INCREASED GAP





# RESULTS

## VALGUS ANGLE CHANGE VERSUS FLEXION ANGLE

